



# Air Vehicle Design AOE 4065 – 4066

#### III. Air Vehicle Design Fundamentals

#### **Course Module A10**

Preliminary Design: Refine & Validate Baseline Design

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#### AOE 4065-4066:

#### Capstone Air Vehicle Design (AVD) Course Modules (CMs)

#### **Overview of AVD Courses**

#### I. Foundational Elements

- F1. Design: An Engineering Discipline
- F2. Systems and Systems Thinking
- F3. Basics of Systems Engineering
- F4. Decision Making with Ethics and Integrity

II. Air Vehicle Design Fundamentals

A1. Purpose & Process

#### **Conceptual Design**

- A2. Understand the Problem
- A3. Solve the Problem
- A4. Initial Sizing: Takeoff Weight Estimation
- A5. Initial Sizing: Wing Loading and Thrust Loading Estimation
- A6. Cost Considerations
- A7. Concept to Configuration: Key Considerations
- A7A. Configuration Layout: Drawings & Loft

#### **Conceptual & Preliminary Design**

- **A8. Trade Studies**
- A9. Use of Software Tools
- A10. Preliminary Design: Baseline Design Refinement & Validation

#### III. Project Management Topics

- P1. Basics of Project Management and Project Planning
- P2. Project Organization
- P3. Roles & Responsibilities of Team Members
- P4. Project Execution: Teamwork for Success
- P5. Project Risk Management
- P6. Delivering Effective Oral Presentations
- **P7. Writing Effective Design Reports**

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## <u>Disclaimer</u>

Prof. Pradeep Raj, Aerospace and Ocean Engineering, Virginia Tech, collected and compiled the material contained herein from publicly available sources solely for educational purposes.
Although a good-faith attempt is made to cite all sources of material, we regret any inadvertent omissions.



# **CRUCIALLY IMPORTANT**

CMs only introduce key topics and highlight some important concepts and ideas...but without sufficient detail. We must use lots of Reference Material\* to add the necessary details! (\*see Appendix in the Overview CM)



## Outline

#### A10. Preliminary Design: Refine & Validate Baseline Design

- A10.1 General Remarks
- A10.2 Integrated System
- A10.3 Aerodynamics
- A10.4 Aeropropulsion Integration
- A10.5 Vehicle Performance
- A10.6 Structures & Materials
- A10.7 Subsystems
- A10.8 Stability & Control
- A10.9 Weights (Mass Properties) & Balance
- A10.10 Cost & Manufacturing



You Generate a More Mature Design in AOE 4066

TRL: Technology Readiness Level

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**Baseline Design in** 

AOE 4065



#### **Capstone Air Vehicle Design Project**

#### The First Day!





The Last Day of



130 ft



# Baseline Design: Recap

We estimated values of parameters for the Baseline Design or the

Preferred System Concept based on many *simplifying assumptions* 

- Initial  $W_{TO}$  Sizing
  - *Empty Weight*: Historical trends for our class of aircraft
  - Fuel Weight: Assumed/estimated values of several parameters
    - AR, (L/D)<sub>max</sub> or C<sub>D0</sub>
    - Cruise and/or loiter speed,  $V_{cr}$  or  $V_{lo}$ ; altitude,  $h_{cr}$  or  $h_{lo}$ ; and *tsfc* or *bsfc* for the cruise or loiter mission phases
- Initial  $(W/S)_{TO}$  and  $(T/W)_{TO}$  Estimation
  - Feasible Design Space (or Domain): Used approximate form of vehicle performance equations to define a Design Space
  - Selected more parameters, such as,  $C_{Lmax}$ ,  $V_{TO}$ , ROC, etc.
- Empennage Sizing
  - Used empirical values of Tail Volume Coefficients
- Component Weights & System Cost
  - Used parametric and empirical relationships
- **Etc., Etc.**

Baseline Design Has Low Level of Maturity (TRL ~ 2-3)



### Baseline Design Needs Refinement & Validation

- Validate <u>all</u> assumptions and parameter values used to create your feasible Baseline Design
  - If the assumptions turn out to be flawed or the parameter values wrong, you may not necessarily have a feasible design, do you?
- Tweak the design to conform to the validated parameters while constantly making sure that the design is feasible
- Develop a project plan that integrates inputs from all sub-teams and disciplines
  - Each sub-team should prepare a list questions that need to be answered.
     For example,
    - What assumptions/ parameters need to be validated? These lead to tasks
    - How do we validate? Defines scope of a task based on desired output
    - <u>When</u> do we need to complete each task? *Defines schedule and milestones*
    - <u>Who</u> else needs the results? *Defines dependencies for scheduling tasks*
  - Each sub-team should prepare a Gantt chart for their own tasks; all subteam charts then roll up into full project level Gantt chart

## Refined Design Has Higher Level of Maturity (TRL ~ 4-5)



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**Initial Sizing** 

- TOGW = Empty Weight
  - + Fuel Weight

+ Fixed (Payload) Weight

<sup>se</sup>Iop down<sup>ss</sup> Estimation of TOGW and its constituents including empty weight Validation Example 1 **Empty Weight** 

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#### **Empty Weight =** $\sum$ **Component Weights**

- Airframe Structure: wing, fuselage, tail, landing gear,...  $\checkmark$
- Propulsion: engine, inlet, fuel system, engine controls,  $\checkmark$ and thrust reversers
- Control system: hydraulic, pneumatic, actuators, ...  $\checkmark$
- <sup>ce</sup>Bottoms up<sup>99</sup> Instruments  $\checkmark$
- Electrical system Analysis of the baseline
- Furnishings design to validate estimated
- Avionics  $\checkmark$
- empty weight Air-conditioning and anti-icing
- Other: drag chutes, etc.

Get precise estimates of CG and Moments of Inertia based on component locations

#### Change in CG affects all subteams!!



- Known weights
- Direct weight estimates •
- Statistical weight estimates



In case you missed it...

"...estimation of the aircraft empty weight is the weakest part of the conceptual design process and it has tremendous leverage on the aircraft takeoff weight. It is almost impossible to estimate the empty weight of something that has not been built...However, it is important to press on or aircraft will never be designed." -- Lee Nicolai

That is why we start with a "Top Down" approach and end with "Bottoms up".

Source: Chapter 5, Ref. 1, (Nicolai & Carichner);



## Validation Example 2 Aerodynamics

# Aerodynamics subteam should review their R&Rs, and any project data deliverables in the RFP

- Identify all parameters that need to be validated and approaches
- $\circ$  Let us consider one of the parameters,  $C_{D0}$ 
  - Do we need to validate the assumed value of  $C_{D0}$ ?
    - ✓ Yes!
  - How will we validate  $C_{D0}$ ?
    - $\checkmark$  Use analysis and testing methods
    - ✓ Research relevant reference material for applicable methods
      - Options include (a) Drag Build-up method which sums up individual component parasitic drag values to estimate aircraft zero-lift drag; or (b) computational methods, such as, FRICTION or VSPAero or some other code to analyze the baseline design; or...
    - Select some or all methods based on available resources and constraints!
- Investigate other parameters, such as, AR,  $S_{ref}$ ,  $(L/D)_{max}$ ,  $C_{Lmax}$ , etc.



#### "Just because you can doesn't mean you should."

#### 1. Understand Customer's Problem

 Develop a comprehensive understanding of the scope of customer needs (potential impact of solution, desired level of accuracy, type and amount of data, etc.) and constraints (cost and schedule)

#### 2. Devise a Practical Approach to Solving the Problem

- Examine available computational simulation codes for solving your problem with *effectiveness* as the key measure of merit
- Choose a code based on your understanding of the problem [the type, amount and quality of aerodynamic data required to meet customer needs subject to the specified constraints]

#### 3. Deliver a Best Solution that Adds Value

Provide a solution that *best* meets customer needs while satisfying all constraints

#### Don't Use a Hammer When You Need a Screwdriver!



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A10.10 Cost & Manufacturing



# A10.2 Configuration Layout and Loft

Configuration Layout and Loft subteam members should review their R&Rs, and any project data deliverables in the RFP



#### Three-view Drawing of RC Airplane: A Good Example Using SAE Specs



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## Final Configuration Layout: A Transport Aircraft Example



Aircraft Specifications		
Max. TOGW (lbs)	453,156	
Seat Capacity	400	
Design Range (nm)	3,500	
Max. Climb Rate (fpm)	5,500	
Cruise Mach No.	0.78	
Cruise Altitude (ft)	40,000	
Service Ceiling (ft)	43,500	





#### An Example to Emulate: Cal Poly SLO Student Team Project

#### Cut-Away View of the C-86 Amarok





## An Example to Emulate: Cal Poly SLO Student Team Project



Source: 2010 AIAA Undergrad Team Competition Winner, Cal Poly, SLO



#### Aircraft Structure & Systems Layout Student Design Project Example to Emulate



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# **Configuration Layout and Loft**

#### **Recommended Reading for Topics in Configuration Layout and Loft**

Торіс	Recommended References
Configuration Layout and Loft	
Configuration Layout and Loft	Chapter 7, Raymer, Ref. AVD 2
Aircraft Design Aid and Layout Guide	All chapters, Kirschbaum with Mason, Ref. AVD 6



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# A10.3 Aerodynamics

#### Aerodynamics subteam members should review their R&Rs, and any project data deliverables in the RFP



# **Role of Aerodynamicist**

## AIAA-82-0315: An Excellent Reference

- o 40 years "new"
- Highly relevant—just replace
   "Tactical-Missile" with Aircraft!
- A copy is in the Aerodynamics
   subfolder on Canvas
- Aerodynamicists help ensure that aircraft delivers targeted flight performance. Period.

AIAA-82-0315 The Changing Role of the Aerodynamicist in Tactical-Missile Design D.R. Carlson, Hughes Aircraft Co., Canoga Park, CA



### AIAA 20th Aerospace Sciences Meeting

🖞 January 11-14, 1982/Orlando, Florida

"They own OML (Outer Mold Line)" – Lee Nicolai



## **Trade Studies**

Empty

Mass

Fuel

Mass









**Trade Studies** 





# **Aerodynamic Coefficients**

#### Estimate Key Non-dimensional Parameters



 $q = Dynamic Pressure = \frac{1}{2}\rho V^2$ 

Reference Areas and Lengths Are Just That — *References* 

#### • Accurate $C_L$ estimation is relatively easy; $C_D$ and $C_m$ not so!



## Broad Categorization of Configuration Aerodynamic Drag





## Zero-lift Drag Build-up

#### **Example: Atlas**



Zero Lift Drag Build-up On Aircraft		
Component	CD0	
Main Wing	0.00507	
Body	0.00855	
Vertical Tail	0.00065	
Horizontal Tail	0.00095	
All Engines	0.00164	
Total:	0.01686	
Initial Sizing:	0.017	

Source: 2023-24 AIAA Heavy Lift Mobility Platform: VT Aero Sub-team Lead: Durgin)

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## **Drag Polars**



**Cambered Wings** 



**Uncambered Wings** 

$$C_D = C_{D_0} + K C_L^2$$

$$C_{D_0} = C_{D_{\min}}$$





## Aerodynamics

#### **Recommended Reading for Topics in Aerodynamics**

Торіс	Recommended References
Aerodynamics	
Review of Practical Aerodynamics	Chapter 2, Nicolai & Carichner, Ref. AVD 1
Selecting the Planform and Airfoil Selection	Chapter 7, Nicolai & Carichner, Ref. AVD 1
High-Lift Devices	Chapter 9, Nicolai & Carichner, Ref. AVD1
Estimating Wing-Body Aerodynamics	Chapter 13, Nicolai & Carichner, Ref. AVD 1
Aerodynamics	Chapter 12, Raymer, Ref. AVD 2 in PR
Wing Design	Chapter 5, Sadraey, Ref. AVD 5
The Anatomy of the Wing	Chapter 9, Gudmundsson, AVD 4
Aircraft Drag Analysis	Chapter 15, Gudmundsson, Ref. AVD 4
Aircraft Drag	Chapter 9, Kundu, Ref. AVD 8
Aircraft Drag and Wing Design	See Aerodynamics folder in Supplemental Reference Material folder on course site



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# A10.4 AeroPropulsion Integration

Aeropropulsion Integration subteam members should review their R&Rs, and any project data deliverables in the RFP



# **Propulsion System Types**

Two main options to produce forward thrust

#### 1. Propellers

- Powered by reciprocating piston engines, gas turbines (<u>turboprops</u>), or electric motors
- Keeping tip speed less than sonic restricts practical use to flight speeds < 500 kt</li>

#### 2. Jet Engines

- Variants include <u>turbojets</u>; afterburning turbojets; and <u>turbofans</u>
- Can operate supersonically to Mach 3.5





## **Onboard Propulsive Efficiency Chains**



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## Turbine Engine Selection Considerations

- Choose a suitable engine that can supply the required thrust
- Realistic propulsion expectations are essential
  - New engines built from scratch are VERY (VERY, VERY, VERY) expensive
    - Deciding to use a 'rubber' engine should take this real cost into account
  - Much of your load is fuel, so you better know how your engine will perform to justify fuel load
  - Real engines have real dimensions, (dry) weights, mass flow rates, inlet and exhaust flow effects, and noise
  - Use extensive engine databases for availability, performance, cost, etc.
- Sometimes new airframes do require new engines to meet stringent efficiency and emissions requirements
  - New technologies enable engines with (i) lean combustion for low Nox; (ii) high-temperature turbine materials for efficiency; (iii) transonic compressor/turbine designs; (iv) noise reducing inlets and exhausts


### Turbine Engine Performance Modeling

Aircraft designers in industry obtain "Engine Decks" built by engine manufacturers that provide engine performance data (thrust, fuel flow, mass flow, pressures and temperatures at specified stations) for a wide range of Mach numbers and altitudes in the flight envelope, sorted by throttle setting



"Engine Decks"--the best performance model!

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Source: Ref. AVD 1 (Nicolai & Carichner)



### Turbine Engine Performance Modeling



Source: Ref. AVD 1 (Nicolai & Carichner)



### **Turbine Engine Inlets**

- Purpose: To slow down oncoming air to speeds suitable for combustion
  - Typical target Mach number is 0.4 to 0.6 at the compressor face





Cruising speed

#### Design Criteria

- o Deliver engine air with minimum distortion
- o Maximize pressure recovery
- Minimize spillage drag throughout the flight regime
- Minimize losses due to flow separation

Installed Performance Greatly Depends Upon Inlet Design

 Strongly recommend looking at Sect. 10.3, Ch. 10, PS 1 (Mattingly) and Sect. 7.3.4, Ch. 7, AVD 4 (Gudmundsson)

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### **Turbine Engine Nozzles**

#### Typical Nozzle Types





### **Turbine Engine Nozzles**

#### Required Nozzle Geometry Variation During Flight



#### Make sure to account for engine installation losses (See Ch. 16 in AVD 1, and also look at AVD 2)



### **Hybrid-Electric Power Train Options**

- Powered by both Batteries (Electrical Energy) and Fossil Fuel
  - Several options for integrating fossilfuel engines with electric motors
  - $\circ~$  All reduce emissions and fuel burn
  - Potential reduction in total energy consumption and total energy cost:
    - ✓ Jet-A: ~\$5 per gallon
    - Electricity: ~\$1.2 per equivalent gallon









Variable pitch controller

### Propulsive Efficiency of a Hybrid Electric (HE) System



https://canvas.vt.edu/courses/143566/files/folder/Project%20Report%20(Spring)/Winning%20Reports%20-%20Past%20Years/VT%20AOE%20Prize%20for%20Excellence?preview=21392423



### **Electric Motors**

- Simple and Reliable (design life of 30,000 hrs. when operated at ~60% rated power)
- Typical specific power: 3 to 5 hp/lb

 Table 14.2
 Electric Aircraft System Data (2010)

Characteristic	Electric Motor	Solar Cell	Fuel Cell	Batteries
Specific energy (kW·h/lb)	0.2ª	NA	0.89 <sup>b,c</sup>	0.27 <sup>c,d</sup>
Design life	30,000 h	е	NA	300 <sup>f</sup>
Efficiency (%) <sup>g</sup>	97	28	55	90
Installed weight (Ib/ft²)	NA	0.1	NA	NA

"Weight includes motor, controller, and propeller. Increase weight by 25% for installation.

<sup>b</sup>H<sub>2</sub>/O<sub>2</sub> regenerative fuel cell using proton exchange membrane technology.

<sup>c</sup>Specific power based on discharge time.

<sup>d</sup>Li–S batteries are projected to increase to 0.336 kWh/lb by 2015.

<sup>e</sup>Solar cells degrade about 1.5% of power output per year.

<sup>1</sup>300 full-depth discharges in 2010. Decreasing the discharge to 50% would increase number of recharges to approximately 1000.

<sup>9</sup>Efficiency is energy out per energy in. Solar cell efficiency is projected to increase to 32% and fuel cell efficiency to 65% by 2015.



### **Battery Characteristics**

Battery Type	Theoretical Specific Energy, W-hr/kg	Practical Specific Energy, W-hr/kg	Specific Power, W/kg	Cell Voltage, V
Lead acid (Pb/acid)	170	30-50	180	1.2
Nickel cadmium (NiCd)	240	60	150	1.2
Nickel metal hydride (NiMH)	470	23-85	200-400	0.94-1.2
Lithium ion (Li-Ion)	700	100-135	250-340	3.6
Lithium polymer (Li-Po)	735	50.7–220	200-1900	3.7
Lithium sulfur (LiS)	2550	350	600-700	2.5



### **Battery Specific Energy & Density**

	Typical Values				
	Chemistry	(Wh/kg)	(Wh/L)	Name	Notes
old	Lead-acid	45	100	Lead acid	automotive
	Alkaline	100	300	Alkoline	flashlights
Nickel	NiFe	25	30	Nickel Iron	locomotives, mining
	NiCd	60	150	Nickel Cadmium	classic "NiCad"
	NiH	75	60	Nickel, Hydrogen	space probes
	NiMH	90	300	Nickel Metal Hydride	replaced NiCad
	NiZn	100	280	Nickel Zinc	automobile, electronics
Li-ion <sup>1</sup>	Li-ion	100-265	250-700	Lithium ion	generic term
	Li-ion Polymer	100-265	250-730	Lithium Polymer	polymer electrolyte
	LiCoO2	200	-	Lithium Cobalt Oxide	handheld electronics
	LiFePO4	120	170	Lithium Iron Phosphate	tools, vehicles
	LiMn2O4	150	-	Lithium Manganese Oxide	laptops, medical equip
	LiNiMnCoO2	260	500	Lithium Nickel Manganese Cobalt Oxide (NMC)	aircraft, road vehicles
	LIS	400	250	Lithium Sulfur	aircraft, road vehicles
	LiS (2020)	500	1000	Licerion <sup>2</sup> (LiS)	aircraft, road vehicles
	Li titonote	90	170	Lithium Titanate	high power/low energy
	Li-air	600	200	Lithium-Air	experimental
misc	Na-ion	150	50	Sodium Ion	laptops, bikes
	Molten salt	220	290	Molten salt	
	Silver Zinc	200	700	Silver Zinc	laptops, hearing aids
Comparisons	Wood	4500	3600	Wood	it floots
	Coal	8000	10000	Coal	it smells
	Jet Fuel	11000	10000	Jet Fuel	love that smell
	Gasoline	12000	9000	Gasoline	too expensive
	LH2	39406	2790	Liquid Hydrogen	too cold
	Uranium	2.2E + 10	4.3E + 11	Uranium	too scary
	Antimatter $(c^2)$	9.0E + 10		Antimatter	beam me up

<sup>1</sup> Lithium-ion is a generic term for various batteries in which lithium ions move to the positive electrode during discharge.
 <sup>2</sup> Licerion is Scion Power's trade name for its patenled rechargeable lithium sulfur battery planned to enter production in late 2018.

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### **Propeller Performance**

(Sect. 14.3 and 14.4, Ch. 14, AVD 4 Gudmundsson)

#### Propeller performance characterized by propeller efficiency and several coefficients:

Sample Propeller Efficiency Map

 $\frac{60 \cdot V_0}{RPM \cdot D}$ 

Propeller efficiency:



#### **Note: See CM A7 for Generic Propeller Maps**

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### **AeroPropulsion Integration**

#### **Recommended Reading for Topics in Aeropropulsion Integration**

Торіс	Recommended References	
AeroPropulsion Integration		
Propulsion System Fundamentals	Chapter 14, Nicolai & Carichner, Ref. AVD 1	
Turbine Engine Inlet Design	Chapter 15, Nicolai & Carichner, Ref. AVD 1	
Corrections for Turbine Engine Installation	Chapter 16, Nicolai & Carichner, Ref. AVD 1	
Propeller Propulsion Systems	Chapter 17, Nicolai & Carichner, Ref. AVD 1	
Propulsion System Thrust Sizing	Chapter 18, Nicolai & Carichner, Ref. AVD 1	
Propulsion	Chapter 13, Raymer, Ref. AVD 2	
Propulsion and Fuel System Integration	Chapter 10, Raymer, Ref. AVD 2	
Propulsion System Design	Chapter 8, Sadraey, Ref. AVD 5	
Selecting the Power Plant	Chapter 7, Gudmundsson, Ref. AVD 4	
The Anatomy of the Propeller	Chapter 14, Gudmundsson, Ref. AVD 4	
Aircraft Power Plant and Integration	Chapter 10, Kundu, Ref. AVD 8	
DEP, Hybrid Electric, Propellers and Open Rotors	See API folder in Supplemental Reference Material folder on course site	



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### A10.5 Vehicle Performance

# Vehicle Performance subteam members should review their R&Rs, and any project data deliverables in the RFP



### Importance of the Role of Vehicle Performance Team

- Predict flight performance for all segments of the mission using appropriate analyses and simulations
- If actual flight performance differs from predictions, adverse project risks include:
  - Loss of Credibility
    - "Cannot Deliver What Was Promised"
  - Potential for Schedule Slip and Additional Cost
    - Flight Test "Surprises" → Schedule Slips and Additional Costs due to Design Modifications
  - Dissatisfied Customer
    - Do Not Like Out-of-Spec Product or Late Delivery or Increased Cost

### Mitigate Risk Through Design, Analysis, and Test



### Flight Performance: Take-off

$$V_{\rm TO} = 1.2 V_{\rm stall} = 1.2 \sqrt{\frac{W_{\rm TO}}{S_{\rm ref}}} \frac{2}{\rho C_{L_{\rm max}}}$$

$$S_G = \frac{1.44 \left( W/S_{\text{ref}} \right)_{\text{TO}}}{g \rho C_{L_{\text{max}}} \left[ \left( T/W \right) - \left( D/W \right) - \mu \left( 1 - L/W \right) \right]}$$

$$\begin{split} D &= (0.5)\rho V^2 S_{\text{ref}} \left[ C_{D_0} + \Delta C_{D_{\text{flap}}} + \Delta C_{D_{\text{gear}}} + K C_{L_G}^2 \right] \\ L &= (0.5)\rho V^2 S_{\text{ref}} C_{L_G} \end{split}$$

 $V = 0.707 V_{\rm TO}$ 

$$S_R = 2V_{\rm TO}$$

$$S_{\rm TR} = R \sin \theta_{\rm CL}$$

$$R = \frac{V_{\rm TO}}{0.15 g}$$

1.00

Rate of climb =  $V_{\text{TO}} \sin \theta_{\text{CL}}$ 



Assumption: unaccelerated climb

Wet grass

Snow- or ice-covered field

## See Sect. 10.3, Ch. 10, AVD 1, for more details and recommended values of parameters



**Brakes Off, Average** Brakes Fully Applied, **Ground Resistance** Average Wheel-Braking Type of Surface Coefficient Coefficient Concrete or macadam 0.015-0.04 0.3-0.6 Hard turf 0.05 0.4 Firm and dry dirt 0.04 0.30 Soft turf 0.07 0.5 Wet concrete 0.05 0.2

0.10

0.01

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0.2

0.07-0.10



### Flight Performance: BFL

#### 1. BFL Estimation\*

$$\begin{split} \mathrm{BFL} &= \frac{0.863}{1+2.3G} \left( \frac{W/S}{\rho g C_{L_{\mathrm{climb}}}} + h_{\mathrm{obstacle}} \right) \left( \frac{1}{T_{\mathrm{av}}/W - U} + 2.7 \right) \\ &+ \left( \frac{655}{\sqrt{\rho/\rho_{\mathrm{SL}}}} \right) \end{split}$$

Jet:

$$T_{\rm av} = 0.75 \ T_{\rm takeoff} \begin{bmatrix} 5 + {\rm BPR} \\ 4 + {\rm BPR} \end{bmatrix}$$
  
static

1

Prop:

$$T_{\rm av} = 5.75 \text{ bhp} \left[ \frac{(\rho/\rho_{\rm SL}) N_e D_p^2}{\text{bhp}} \right]^{\frac{1}{3}}$$

BFL = balanced field length (ft)

 $G = \gamma_{\text{climb}} - \gamma_{\text{min}}$   $\gamma_{\text{climb}} = \arcsin \left[ (T-D)/W \right], 1 - \text{engine-out, climb speed}$   $\gamma_{\text{min}} = 0.024$  2-engine; 0,027 3-engine; 0.030 4-engine  $C_{L_{\text{climb}}} = C_L$  at climb speed (1.2  $V_{\text{stall}}$ )

 $h_{\rm obstacle} = 35$  ft commercial, 50 ft military

 $U = 0.01 C_{L_{max}} + 0.02$  for flaps in takeoff position BPR = bypass ratio

bhp = engine brake horsepower

 $N_e$  = number of engines

 $D_p = \text{propeller diameter (ft)}$ 

#### 2. More Accurate BFL Estimation\*\*

- $\circ$  Assume failure recognition speed V<sub>EF</sub>
- $\circ$  Calculate LAB: accelerate to V<sub>EF</sub>, free roll for 3 sec., brake to full stop
- Calculate LAC: accelerate to V<sub>EF</sub>, continue OEI takeoff over 35 ft. obstacle
- Estimate refusal speed,  $V_{EF}$ , when LAB = LAC



#### \*See Sect. 17.8, Ch. 17, AVD 2 \*\*See Sect. 10.6, Ch. 10, AVD 1



### Flight Performance: Climb

• Rate of Climb (ROC)

$$V \sin \gamma = \frac{P_S}{1 + (V/g)(dV/dh)}$$
$$P_S = \frac{dh_e}{dt} = \frac{V \Big[ T \cos(\alpha + i_T) - D \Big]}{W}$$

Constant Speed Climb

$$V\sin\gamma = \frac{V\left[T\cos\left(\alpha + i_T\right) - D\right]}{W}$$

- Best ROC (maximum vertical velocity)
  - o Jet aircraft

$$V = \sqrt{\frac{W/S}{3\rho C_{D_0}}} \left[ T/W + \sqrt{(T/W)^2 + 12C_{D_0}K} \right]$$

- Best Angle of Climb (maximum γ)
  - o Jet aircraft

$$V = \sqrt{\frac{2W}{\rho S} \sqrt{\frac{K}{C_{D_0}}}}$$



Assumption: all angles are small

#### • Propeller aircraft

$$V = V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

- Propeller aircraft
  - 85-90% of best ROC speed is a good estimate

#### See Ch. 3, AVD 1, and Ch. 17, AVD 2 for more details



### Flight Performance: Descent

Gliding Flight (T = 0)

 $\gamma = \arcsin\left(-D/W\right)$ 

$$\gamma = \arctan\left(-D/L\right)$$

• Maximum Range (minimum γ,

$$V = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{C_{D_0}}}$$

• Maximum Endurance (minimum rate of descent, ROD)

$$V_{\rm ROD_{min}} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

#### See Ch.3, AVD 1 (Nicolai & Carichner), for more details



### Flight Performance: Landing

$$S_A = \frac{L}{D} \left[ \frac{V_{50}^2 - V_{\text{TD}}^2}{2g} + 50 \right]$$

 $V_{50} = 1.3 V_S$   $V_{TD} = 1.15 V_S$ 

 $L = W_L$  = aircraft weight with 1/2 fuel remaining

 $C_{L_{\text{land}}} = C_{L_{\text{max}}}$  for flaps in landing configuration

$$V_{50}$$

$$V_{TD}$$

$$V=0$$

$$V=0$$

$$S_{A} \rightarrow S_{FR} = S_{B} \rightarrow V$$

$$C_{D} = C_{D_{0}} + KC_{L_{\text{max}}}^{2} + \Delta C_{D_{\text{flaps}}} + \Delta C_{D_{\text{gear}}}$$

 $S_A = 50/\tan \theta_{app}$ ,  $\theta_{app} = approach glide slope (3 deg for typical CTOL, 7 deg for STOL)$ 

$$S_{\rm FR} = 3V_{\rm TD} \qquad S_B = \frac{W_L}{g\mu\rho S_{\rm ref} \left[ (C_D/\mu) - C_{LG} \right]} \ln \left[ 1 + \frac{\rho}{2} \frac{S_{\rm ref}}{W_L} \left( \frac{C_D}{\mu} - C_{LG} \right) V_{\rm TD}^2 \right]$$

$$C_{D} = C_{D_{0}} + KC_{L_{G}}^{2} + \Delta C_{D_{\text{flaps}}} + \Delta C_{D_{\text{gear}}} + \Delta C_{D_{\text{misc}}} + \Delta C_{D_{\text{spoilers}}}$$

Assumptions:

Neglect reverse thrust

Zero forward thrust

Type of Surface	Brakes Off, Average Ground Resistance Coefficient	Brakes Fully Applied, Average Wheel-Braking Coefficient
Concrete or macadam	0.015-0.04	0.3–0.6
Hard turf	0.05	0.4
Firm and dry dirt	0.04	0.30
Soft turf	0.07	0.5
Wet concrete	0.05	0.2
Wet grass	0.10	0.2
Snow- or ice-covered field	0.01	0.07-0.10

## See Section 10.4, AVD 1, for more details and recommended values of parameters

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### Flight Performance: Cruise & Loiter

Level unaccelerated flight of symmetric aircraft with uncambered wing

$$W \approx L = C_L qS$$
  $T \approx D = \left(C_{D_0} + K C_L^2\right) qS$ 

$$\frac{T}{W} = \frac{1}{L/D} = \frac{qC_{D_0}}{(W/S)} + \left(\frac{W}{S}\right)\frac{K}{q}$$

Required Thrust and Power

 $T_R = D = C_{D_0} q S + K W^2 / q S$ 

$$P_R = DV = T_R V = \left(C_{D_0} + K C_L^2\right) \frac{W}{C_L} \sqrt{\frac{2W}{\rho C_L S}}$$

Range

$$R = \frac{V}{C} \frac{L}{D} \ln \left[ \frac{W_i}{W_f} \right]$$

- <u>Jet</u> aircraft
  - Most Efficient cruise occurs near  $L/D = 0.943 (L/D)_{max}$  (constant throttle)  $L/D = 0.866 (L/D)_{max}$  (constant altitude)
  - **Most Efficient loiter** occurs near  $L/D \sim (L/D)_{max}$  (minimum thrust)

$$E = \frac{L}{D} \frac{1}{C} \ln \left[ \frac{W_i}{W_f} \right]$$

- Propeller aircraft
  - **Most Efficient cruise** occurs near  $L/D = (L/D)_{max}$  (minimum thrust)
  - **Most Efficient loiter** occurs near  $L/D = 0.866 (L/D)_{max}$  (minimum power)



### Flight Performance: Cruise & Loiter

#### • Max Loiter (Jets) and Max Range (Propellers)

$$V_{(L/D)_{\text{max}}} = \sqrt{\frac{2W}{\rho C_{L_{opt}}S}} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{C_{D_0}}}$$

$$Max \text{ Range Speed (Jets)}$$

$$V_{\text{best range}} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{3K}{C_{D_0}}}$$

$$C_L$$

$$Max \text{ Loiter (Propellers)}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

$$Max \text{ Loiter (Propellers)}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

$$Max \text{ Loiter (Propellers)}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

$$V_{\min P_R} = \sqrt{\frac{2W}{\rho S}} \sqrt{\frac{K}{3C_{D_0}}}$$

•

•



### **Vehicle Performance**

#### **Recommended Reading for Topics in Vehicle Performance**

Торіс	Recommended References	
Vehicle Performance		
Aircraft Performance Methods	Chapter 3, Nicolai & Carichner, Ref. AVD 1	
Takeoff and Landing Analysis	Chapter 10, Nicolai & Carichner, Ref. AVD 1	
Performance and Flight Mechanics	Chapter 17, Raymer, Ref. AVD 2	
Performance (GA Aircraft)	Chapters 16 thru 22, Gudmundsson, Ref. AVD 4	
Aircraft Performance	Chapter 13, Kundu, Ref. AVD 8	
Aircraft Flight Performance	Chapters 1 thru 16, Filippone, Ref. FM 4	
Aircraft Noise and Emissions	Chapters 17 thu 23, Filippone, Ref. FM 4	
Performance	See Performance folder for misc documents in Supplemental Reference Material on course site	



### Outline

#### A10. Preliminary Design: Refine & Validate Baseline Design

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A10.10 Cost & Manufacturing



### 10.6 Structures & Materials

# Structures & Materials subteam members should review their R&Rs, and any project data deliverables in the RFP

### **Structural Design Criteria**



## • Loads Engineers develop a set of external loads (aerodynamic and inertia loads) that a 'lightest weight' structure must withstand without failing

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Source: Ch 19, Ref. AVD 1 (Nicolai & Carichner)



### **Typical V-n Diagram**

#### Student Design Team Example





### **External Loads Development Process**





### **Aircraft Structure & Systems Layout**







#### Aircraft Structural Layout Example Student Design Team Example to Emulate





### **Typical Wing Box:** *Structural Components*

A wing box is made of three structural members: wing skin, spars, and ribs.

Wing skin panels are located on the top and bottom of the wings. Skin can aid in the reaction of bending moments, but it primarily carries shear loading.

**Spars** are members that run along the span of the wing and react carry bending and shear loads from lift.

**Ribs** run across the spars and they give form to the wing covers as well as prevent buckling of the wing covers.



Source:

Arevalo, PT, "Design Optimization of a Composite Wing Box for a High-Altitude Long-Endurance Aircraft," Ph.D. Thesis, Embry-Riddle Aeronautical University, Florida, May 2014



**C-130 Center Wing Box** 



Source: Strul, E., "IAI C-130 Life Extension Program CWB Replacement," C-130 Hercules Operators Council, 2013

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### **Typical Wing Structural Layout**



#### Refine/validate Structural Layout Through Analyses

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Source: Ch. 5, Ref. AVD 4 (Gudmundsson)



### **Structural Design Rules of Thumb**

- 1. Keep load paths simple and direct
- 2. All six components of structural loading must be considered
- 3. A statically determinate structure is usually preferred for minimum weight (Fail safe requirements might dictate a statically indeterminate design)



- 4. Each structural component should serve multiple functions
- 5. Subsystems integration requirements must be considered early



### **Materials Selection**

- One of the most important decisions with far-reaching implications for vehicle weight, performance, manufacturing schedule, reliability, maintainability, and cost
- Key parameters to consider in selecting airframe materials include:
  - o specific strength—ultimate tension strength ( $F_{tu}$ ) divided by material density
  - specific stiffness—Young's modulus (E) divided by density
  - o operational environment—for example temperature range, humidity, etc.
  - o fracture toughness ( $K_{IC}$ )—inherent capability to resist crack growth
  - o manufacturability—ability to fabricate an end product using standard tools and methods
  - o minimum gage limitations—minimum thickness to which material can be produced
  - o availability—long lead times from several months to well over a year



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Source: Ch. 19, Ref. AVD 1 (Nicolai & Carichner)



### Aerospace Advanced Composite Usage

Structural Weight Consisting of Advanced Composites



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Source: Arris Composites, Inc. (Alex Huckstepp, LinkedIn post, July 2020)


# **Structures & Materials**

#### **Recommended Reading for Topics in Structures & Materials**

Торіс	Recommended References		
Structures & Materials			
Structures and Materials	Chapter 19, Nicolai & Carichner, Ref. AVD 1		
Structures and Loads	Chapter 15, Raymer, Ref. AVD 2		
Aircraft Structural Layout	Chapter 5, Gudmundsson, Ref. AVD 4		
Aircraft Loads	Chapter 5, Kundu, Ref. AVD 8		
Airframe Structural Design	Book by Michael C.Y. Niu, Ref. STR 1		
Composite Airframe	Book by Michael C.Y. Niu, Ref. STR 2		
Structural Sizing	See Structures folder in Supplemental Reference Material on course site		



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A10.10 Cost & Manufacturing



# 10.7 Subsystems

# Subsystems subteam members should review their R&Rs, and any project data deliverables in the RFP



# **Subsystems**

#### Typical Air Vehicles Subsystems

- Landing Gear
- Crew station requirements and cockpit layout
- Avionics system
- Flight control system and actuators
- Passenger and cargo arrangement (volume and weight)
- Weapons system if appropriate
- Environmental Control System (ECS)
- Thermal Management System
- Fuel system
- De-icing system
- ...

#### In Conceptual Design phase:

- Focus on relevant technology developments and current systems used
- Concentrate on SWaP, i.e., size (volume), weight, and power requirements
- In Preliminary Design phase:
  - Select <u>specific</u> systems with *actual* SWaP values



The following slides show examples of subsystems integration—many from previous years' student design reports—to illustrate the nature of deliverables expected of the Air Vehicle Subsystems team at the end of the project.



# **More Electric Aircraft Subsystems**

#### Electrification of Subsystems Ice-Protection Systems: WIPS: Electro-Mechanical Eliminates heavy, bleed-air architecture 2x250 kVA generators per engine with Expulsion de-icing variable frequency generation CIPS; bleed-air provides ~60% system weight reduction WING BOX CREW ESCAPE HATCH ENA'S AND TORQUE DRIVEN TUBES CABIN APU AIRCUPT C.O. FUEL C.G. ~- when AVIONICS BAY N.L.G L.G. FUEL CARGO CARGO FUEL RADAR LATRU'S AND AFT LE BAY -ECS COMPRESSORS BULK CARGO 4 POWER DISTRUBUTION/LIQUID COOLING PACKS-FF BA Flight Control System: ECS and Power Dist.: APS5000 450 kVA APU: Duplex FBW system with Electric, adjustable A/C Lowest emissions and conventional control and Liquid cooling for noise levels available yoke feedback. primary panels Electric subsystems will reduce maintenance, and fuel consumption by 3% CHRO 12 28 April 2020.



Landing Gear





# Landing Gear

Integration Criteria	Requirement	SWIFT-Jet
Take-Off Clearance( $\alpha_C$ )	$\alpha_C \ge \alpha_{TO} = 9^{\circ}$	12.8°
Steering Controllability	$\frac{Bm_m in}{B} \ge 5\% \& \frac{Bm_m ax}{B} \le 20\%$	5.3% & 9.2%
Tip Back $(\alpha_{tb})$	$\alpha_{tb} \ge \alpha_{TO} + 5^\circ = 14.2^\circ$	20.8°
$Overturn(\Phi_{OT})$	$\Phi_{OT} \ge 25^{\circ}$	31.7°





### **Crew Station**





### **Crew Station**









#### NHA PDR | 4/27/21 | 17



# B757-300 Cockpit Plan





# F-16 Cockpit: Avionics Layout





# **Flight Crew Interface/Control**



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# **Garmin G-3000 Avionics Architecture**





# **FCS Integration**

# Flight Control System: Fly-By-Wire





# Key Components of Fly-By-Wire System

Fly By Wire System	Power Demand (Watts)	Weight (Ibs)
Rockwell-Collins Flight Computer	175	14
(8x) Moog 863 Rotary Servo Actuators (+/- 45 deg @ 150 in-lb torque)	16	14.4
iMAR Inertial Measurement Sensor	35	18.7
Septino GNSS (Global Navigation Satellite System)	6	2.2
(3x) Simtec ADS-7 Heated Air Pitots	120	13.2
FJ33 Engine FADEC	200	11
Totals	552	73.5















#### SWIFT-Jet seamlessly integrates within existing infrastructure to solve worldwide airport congestion

WIDTH: 18"

PITCH: 36'

WIDTH: 21"

(CARGO X-SECTION)

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# Electric Power Generation & Distribution to Major Subsystems



TRAS – Thrust Reverser Actuation System

FCAS – Flight Control Actuation System WIPS – Wing Ice Protection System



# Electric & Hydraulic Systems Integration





# **Fuel System Architecture**



The fuel system will ensure both engines receive the necessary amount of fuel to produce the required thrust throughout the flight envelope





# **A Typical Aircraft Thermal Management System (TMS)**



## TMS detailed design usually deferred to later stages of the Design Cycle

PAO: polyalphaolefin



# **Air Vehicle Subsystems**

#### **Recommended Reading for Topics in Air Vehicle Subsystems**

Торіс	Recommended References		
Air Vehicle Subsystems			
Crew Station, Passengers, and Payload	Chapters 9 & 11, Raymer, Ref. AVD 1		
Fuselage Design	Chapter 7, Sadraey, Ref. AVD 5		
Systems Architecures	Chapter 5, Moir & Seabridge, Ref. AS 1		
Aircraft Systems Examples	Chapter 10, Moir & Seabridge, Ref. AS 1		
Power Systems Issues	Chapter 11, Moir & Seabridge, Ref. AS 1		
Key Characteristics of Aircraft Systems	Chapter 12, Moir & Seabridge, Ref. AS 1		
Aircraft Subsystems Integration	Book by Moir and Seabridge, Ref. AS 2		
Civil Avionics Systems	Book by Moir and Seabridge, Ref. AS 3		
Military Avionics Systems	Book by Moir and Seabridge, Ref. AS 4		
Undercarriage	Chapter 7, Kundu, Ref. AVD 8		
Landing Gear and Subsystems	Chapter 11, Raymer, Ref. AVD 2		
Landing Gear Design	Chapter 9, Sadraey, Ref. AVD 5		
The Anatomy of the Landing Gear	Chapter 13, Gudmundsson, Ref. AVD 4		
Aircraft Landing Gear Design	Book by Currey, Ref. AS 5		
Fuselage, Fuel Systems and Landing Gear	See Subsystems folder in Supplemental Reference Material folder on course site		



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# A10.8 Stability & Control

# Stability & Control (S&C) subteam members should review their R&Rs, and any project data deliverables in the RFP



# Provide Evidence that the Design Meets S&C Requirements

- FAR Requirements on Stability are comparatively vague by design
- MIL-F-8785C provides more useful numbers for requirements
  - Based on aircraft class (Transport, Fighter) and Flight Phase
- Roll Control in time to certain bank angle (Dependent on class)
- Pitch Control in takeoff rotation at Stall Speed in 3-5s at specified angular rate

Dynamic Mode	MIL Stability Requirement
Phugoid	$\zeta_{ph} \ge 0.04$
Short Period	$0.3 \geq \zeta_{ m sp} \leq 2.0$
Roll Subsidence	$T_R \le 1.4$
Spiral	$\mathrm{T}_{2s} \geq 20$
Dutch Roll	$\zeta_d \ge 0.08$



# **Aircraft Trim vs Control**

- Separate systems for each or a single system that provides both?
  - Adjustable elevators, flaps, trim tabs
  - Define their respective regimes and ensure compatibility



https://fl360aero.com/detail/aircraft-pitch-trim-system-how-does-a-stab-trim-or-trimmable-horizontal-stabilizer-work/276



https://airplaneacademy.com/aircraft-trim-explained-with-pictures/



# **Scissor Plot (X-plot) Example**



Source: https://www.fzt.haw-hamburg.de/pers/Scholz/HOOU/AircraftDesign\_11\_EmpennageSizing.pdf

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### **Scissor Plot (X-plot) Example**



Source: https://www.semanticscholar.org/paper/FLYING-QUALITIES-CONSTRAINTS-IN-THE-DESIGN-OF-A-Morris-Schetz/6eee07c8221cccdd2f3060f044c5b33a086e4e40/figure/6



# **Stability & Control**

#### **Recommended Reading for Topics in S&C**

Торіс	Recommended References		
Stability & Control			
Static Stability and Control	Chapter 21, Nicolai & Carichner, Ref. AVD 1		
Trim Drag and Maneuvering Flight	Chapter 22, Nicolai & Carichner, Ref. AVD 1		
Control Surface Sizing Criteria	Chapter 23, Nicolai & Carichner, Ref. AVD 1		
Stability, Control, and Handling Qualities	Chapter 16, Raymer, Ref. AVD 2		
The Anatomy of the Tail	Chapter 11, Gudmundsson, Ref. AVD 4		
Tail Design	Chapter 6, Sadraey, Ref. AVD 5		
Design of Control Surfaces	Chapter 12, Sadraey, Ref. AVD 5		
Stability Considerations Affecting Aircraft Configuration	Chapter 12, Kundu, Ref. AVD 8		
Boeing S&C Course Notes and Empennage Design	See Stabilty & Control folder in Supplemental Reference Material on course site		



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A10.10 Cost & Manufacturing



# A10.8 Weights (Mass Properties) & Balance

# Weights & Balance subteam members should review their R&Rs, and any project data deliverables in the RFP



# **Weight Estimation Methods**





# Final "Weight Statement"

Table 1. ACSYNT'S DATABASE PROVIDED A BOEING 737-300 WEIGHT STATEM

	Item			Weight	
	Airframe Structure			36,392. Ibs	Π
	Wing		11,837.		
	Fuselage		14,325.		
	Horizontal Tail		1,737.		
	Vertical Tail		1,092.		
	Nacelles		1,997.		
	Landing Gear	1 920	5,494.		
	Main	3,654			
	Propulsion	3,004.		9 693	
	Engines		8.460	3,033.	
	Fuel System		705		
	Thrust Reversers		532.		
	Fixed Equipment			23,216.	
Empty Weight –	Hydraulics & Pneumatics		592.		
	Electrical		4,042.		
	Avionics		2,362.		Operating
	Instrumentation		780.		- perating
	De-Icing & Air Conditioning		1,546.		Empty
	Auxiliary Power System		877.		
	Furnishings & Equipment		11,523.		Weight
	Seats & Lavatories	6,160.			-
	Galleys Misselley actor Coolwit Furnishings	1,820.			
	Cabin Euroisbings	234.			
	Cabin Emergency Equipment	2,501.			
	Cargo Handling	350			
	Flight Controls	000.	1 599		
	Empty Weight		1,0001	69.301. lbs	
	Operating Items		3,305.		
	Flight Crew	340.			
Operating Empty Weight —	Crew Baggage & Provisions	175.			
	Flight Attendants	520.			
	Unusable Fuel & Oil	310.			
	Passenger Service	1,960.			
	Cargo Containers	0.		70.000	
Eucl Weight	Operating Weight Empty		27 205	72,606.	
ruel weight	Payload		37,205. 28,000		
Devload Weight	Passonners		23,000.		
rayioad weight –	Baddade		4 200		
	Cargo		-,200.		
Takeoff Gross Weight ——	→TakeOff Gross Weight			137,811. Ibs	

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# Weight & Moment Summary

#### Table 20.1 Weight and Moment Summary

Component	Weight (lb)	Distance from Aircraft Nose (ft)	Moment (ft-lb)
Fuselage			
Wing			
Main gear			
Vertical tail			
Horizontal tail			
etc.			
	ΣWt	Total moment =	ΣΜ

 $X_{c.g.} = \text{Total Moment}/\Sigma\text{Wt}$ 

- C.G. location reported as distance from the nose and % MAC
- Determine C.G. location for full and empty aircraft and report as most forward and most aft locations



# C.G. Travel Example (F-4D)



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Source: Fig. 23.2, Chapter 23, AVD 1 (Nicolai & Carichner)



# **Boeing 777 C.G. Limits**




## Weights & Balance

#### **Recommended Reading for Topics in Weights & Balance**

Торіс	Recommended References
Weights & Balance	
Refined Weight Estimate	Chapter 20, Nicolai & Carichner, Ref. AVD 1
Weights	Chapter 15, Raymer, Ref. AVD 2
Weight Control and Balance	Chapter 16, Niu, Ref. AS 1
Aircraft Weight and Center of Gravity Estimation	Chapter 8, Kundu, Ref. AVD 8
Aircraft Weight Analysis	Chapter 6, Gudmundsson, Ref. AVD 4
Weight of Components	Chapter 10, Sadraey, Ref. AVD 5
Aircraft Weight Distribution	Chapter 11, Sadraey, Ref. 9 in PR
CG Limits and Weights & Balance	See Weights & Balance folder in Supplemental Reference Material on course site



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#### A10.10 Cost & Manufacturing



## A10.10 Cost & Manufacturing

# Cost & Manufacturing subteam members should review their R&Rs, and any project data deliverables in the RFP



## **Cost & Manufacturing**

- Cost estimation: The Critical Area—Start Early!
- All Team members should factor in cost considerations of their assigned area into every decision
- See CM A6
- Manufacturing planning





## **Cost & Manufacturing**

#### **Recommended Reading for Topics in Cost & Manufacturing**

Торіс	Recommended References
Cost & Manufacturing	
Life Cycle Cost	Chapter 24, Nicolai & Carichner, Ref. 1 in PR
Cost Analysis	Chapter 18, Raymer, Ref. 2 in PR
Aircraft Cost Analysis	Chapter 2, Gudmundsson, Ref. 10 in PR
Aircraft Cost Considerations	Chapter 16, Kundu, Ref. 8 in PR
Design for Manufacturing	Chapter 2, Niu, Ref. 24 in PR
Composite Manufacturing	Chapters 3 & 4, Niu, Ref. 25 in PR
Aircraft Manufacturing Considerations	Chapter 17, Kundu, Ref. 8 in PR
Cost Estimation & Manufacturing Consideerations	See Cost and Manufacturing folders in Supplemental Reference Material on course site